Finite reflection groups, hyperplane arrangements, and (oriented) matroids

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1. Introduction

To be written...

CHAPTER 1

Finite reflection groups

1. The symmetric group

The symmetric group \mathfrak{S}_n is set of bijections from $[n] := \{1, 2, ..., n\}$ to itself. We can all agree that permutations and their combinatorics are ubiquitous throughout all of mathematics. Here we recall the basic properties of \mathfrak{S}_n and view it as a group generated by reflections in hyperplanes.

We represent a permutation $\sigma: [n] \to [n]$ in **one-line** notation, which is the bottom row of the table

Thus $\sigma = 467193528$. The set of bijections becomes a group under composition. So, for example, for $\tau = 581639274$, the product with σ is $\sigma\tau = 924378651$. Alternatively, we write σ in cycle notation $\sigma = (14)(2637598)$. Fixed points, i.e., cycles of length 1 are usually omitted.

A transposition is a permutation that swaps two numbers i and j and leave all others fixed. We denote such a transposition by (i, j). Note that $(i, j)\sigma$ swaps the numbers i and j in the one-line notation, while $\sigma(i, j)$ swaps the entries at positions i and j.

$$(7,9)\sigma = 469173528$$

 $\sigma(7,9) = 467193825$

Also note that $\sigma(i, j) = (\sigma(i), \sigma(j))\sigma$ for all i < j.

The symmetric group is generated by **transpositions**. In fact, \mathfrak{S}_n is generated by **adjacent** (or **simple**) transpositions, that is, the n-1 transpositions of the form $s_i = (i, i+1)$ for $i = 1, \ldots, n-1$. For example,

This is a **reduced expression**, in the sense that it uses the minimal number of simple transpositions. Reduced expressions are in general not unique. For σ there are 5630196 many distinct reduced expressions. The number of simple transpositions used is independent of the reduced expression and called the **length** $\ell(\sigma)$. An **inversion** of σ is a pair (i, j) with $1 \le i < j \le n$ and $\sigma(i) > \sigma(j)$. The **inversion number** inv (σ) is the number of inversions.

Exercise 1.1. Let $\sigma \in \mathfrak{S}_n$ be a permutation.

- (1) Show that $\ell(\sigma) = inv(\sigma)$.
- (2) Find a procedure to generate all reduced expressions.

We can view permutations as acting on \mathbb{R}^n . For $\sigma \in \mathfrak{S}_n$, define $P_{\sigma} \in \mathbb{R}^{n \times n}$ by

$$(P_{\sigma})_{i,j} = \begin{cases} 1 & \text{if } i = \sigma(j) \\ 0 & \text{otherwise.} \end{cases}$$

If e_1, \ldots, e_n are the standard basis vectors of \mathbb{R}^n , then $P_{\sigma}e_i = e_{\sigma(i)}$ and hence $P_{\sigma}P_{\tau} = P_{\sigma\tau}$. Note that $(P_{\sigma})^{-1} = P_{\sigma^{-1}} = P_{\sigma}^t$ and hence P_{σ} is an *orthogonal* matrix with respect to the standard inner product

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 $\langle x, y \rangle = x_1 y_1 + \dots + x_n y_n$ on \mathbb{R}^n . So, for our σ we get

Note that for a transposition (i, j), $P_{(i,j)}v = v$ if and only if $v_i = v_j$. That is, $P_{(i,j)}$ acts as the identity on the linear hyperplane $H_{ij} = \{v \in \mathbb{R}^n : v_i = v_j\}$. Moreover, $P_{(i,j)}$ is the reflection in the hyperplane H_{ij} in the sense that $v - P_{(i,j)}(v)$ is perpendicular to H_{ij} . Thus, we can view \mathfrak{S}_n as a finite group of linear transformations that is generated by reflections in hyperplanes.

As a sneak peek, let us see how the geometry of the arrangement of the $\binom{n}{2}$ hyperplanes $H_{i,j}$ reflects properties of \mathfrak{S}_n . A point $v \in \mathbb{R}^n$ is not contained in any of the hyperplanes $H_{i,j}$ if and only if $v_i \neq v_j$ for all i < j. Hence, there is a unique permutation σ such that

$$v_{\sigma(1)} < v_{\sigma(2)} < \cdots < v_{\sigma(n)}$$

Moreover, u is in the same connected component of $\mathbb{R}^n \setminus \bigcup_{i < j} H_{i,j}$ if and only if u is contained in the open convex set

$$C_{\sigma} = \{ v \in \mathbb{R}^n : v_{\sigma(1)} < v_{\sigma(2)} < \dots < v_{\sigma(n)} \}$$

Thus

$$\mathbb{R}^n \setminus \bigcup_{i < j} H_{i,j} = \bigcup_{\sigma \in \mathfrak{S}_n} C_{\sigma}$$

and since $C_{\sigma} = P_{\sigma}(C_{id})$, any two sets C_{σ} are isometric.

2. Reflections and reflection groups

Let V be an n dimensional real vector space with inner product $\langle ., . \rangle$. A **linear hyperplane** is a linear subspace of dimension n - 1. That is, H is of the form

$$H = H_{\alpha} = \{ v \in V : \langle \alpha, v \rangle = 0 \}$$

for some $\alpha \in \mathbb{R}^n \setminus 0$. Note that α is unique up to scaling. The (orthogonal) **reflection** in H is the linear transformation $s_H : V \to V$ such that $s_H(v) = v$ for all $v \in H$ and $s_H(\alpha) = -\alpha$. This allows us to give an explicit description of s_H as

$$s_H(v) = v - \frac{2\langle \alpha, v \rangle}{\langle \alpha, \alpha \rangle} \alpha.$$
 (1)

This does not depend on the choice of α but it is customary to write this as s_{α} . In particular $s_{\alpha}^2 = \text{id}$ and s_{α} is an element of the orthogonal group $O(V) = \{g \in \text{GL}(V) : \langle g(u), g(v) \rangle = \langle u, v \rangle \text{ for all } u, v \in V \}.$

A finite reflection group is a finite group of linear transformations $W \subseteq GL(V)$ that is generated by (orthogonal) reflections in hyperplanes.

If W is generated by a single reflection, then $W = \{e, s_{\alpha}\}$.

To get a feeling, let us consider the case that W is generated by two reflections s_{α} and s_{β} . Now α, β are linearly independent and span a 2-dimensional subspace $L = \operatorname{span}\{\alpha, \beta\}$. Since $V = L \oplus L^{\perp}$, and s_{α}, s_{β} restrict to the identity on L^{\perp} , it suffices to consider the case $V = \mathbb{R}^2$. More generally, if W is a reflection group, then the **fixed space** is $V^W := \{u \in V : wu = u \text{ for all } w \in W\}$ and we can restrict the action of W to $(V^W)^{\perp}$. If $V^W = \{0\}$, then we call W essential (relative to V). The **rank** of W is the dimension $\dim(V^W)^{\perp} = \dim V - \dim V^W$. Hence, if W is minimally generated by 2 reflections, then W is of rank 2. Let $\alpha, \beta \in \mathbb{R}^2 \setminus 0$. Let θ be the angle between H_{α} and H_{β} . The angle satisfies $\theta = \pi - \angle(\alpha, \beta) = \pi - \cos^{-1}\left(\frac{\langle \alpha, \beta \rangle}{\sqrt{\langle \alpha, \alpha \rangle \langle \beta, \beta \rangle}}\right)$. Figure 1 shows the situation. If v has angle ω to the line H_{α} , then $\angle(v, s_{\alpha}(v)) = 2\omega$.

Likewise, if the angle between $s_{\alpha}(v)$ and H_{β} is γ , then $\angle (s_{\alpha}(v), s_{\beta}(s_{\alpha}(v))) = 2\gamma$. Since $\omega + \gamma = \theta$, we infer that $\angle (v, s_{\beta}(s_{\alpha}(v))) = 2\omega + 2\gamma = 2\theta$. Thus $s_{\beta}s_{\alpha}$ is a rotation by 2θ .



FIGURE 1. The composition of two reflections in the plane is a rotation.

Now if W is finite, then there is (a minimal) $m \ge 2$ such that $(s_\beta s_\alpha)^m = \text{id.}$ Such an m must satisfy $m\theta = \ell\pi$ for some $\ell \ge 1$.

Proposition 2.1. Let H_{α}, H_{β} be hyperplanes with an angle $\frac{k}{\ell}\pi$ between them. Let W be the reflection group generated by s_{α} and s_{β} . Then there is a reflection $s_{\gamma} \in W$ whose hyperplane H_{γ} has an angle of $\frac{1}{\ell}\pi$ to H_{α} and s_{α}, s_{γ} generate W.

PROOF. We can assume that k and ℓ are coprime and hence there is an r > 0 such that $rk = q\ell + 1$ for some q. Thus $w := (s_\beta s_\alpha)^r$ is a rotation by $\frac{2}{\ell}\pi$. Consider $w' := ws_\alpha \in W$. This is a reflection (check this!) in some hyperplane H_γ , i.e., $w' = s_\gamma$ and $w's_\alpha$ is a rotation of $\frac{2}{\ell}\pi$. Thus H_γ and H_α have an angle of $\frac{1}{\ell}\pi$ and $s_\beta s_\alpha = (s_\gamma s_\alpha)^k$, that is, $s_\beta = (s_\gamma s_\alpha)^k s_\alpha = (s_\gamma s_\alpha)^{k-1} s_\gamma$.

We can always assume that W is generated by reflections in hyperplanes with angle $\frac{\pi}{m}$ between them.

If m = 2, then $\alpha \perp \beta$, that is, $\alpha \in H_{\beta}$ and $\beta \in H_{\alpha}$. Hence $s_{\alpha}s_{\beta} = s_{\beta}s_{\alpha}$ and $W = \{ id, s_{\alpha}, s_{\beta} \}$.

If $m \geq 3$, then pick $u_1 \in H_{\alpha} \setminus 0$. The orbit $Wu_1 = \{wu_1 : w \in W\}$ will consist of m points u_1, u_2, \ldots, u_m (why? \otimes), which are the vertices of a regular polygon Q_m (why?? \otimes). The group W is the symmetry group of Q_m , called the **dihedral group**, denoted by \mathcal{D}_m . The number of elements of \mathcal{D}_m is 2m.

Exercise 2.2. Answer the two questions marked \leq in the paragraph above.

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This gives a complete classification of rank-2 reflection groups.

Notice that for any $m \ge 2$ if u is not contained in any of the reflection hyperplanes of W, then Wu are the vertices of a 2m-gon that is not necessarily regular and for which W is not the symmetry group. We'll get back to these polygon much later.

Generally, if W is a finite reflection group and $s_{\alpha}, s_{\beta} \in W$ are two reflections, then the subgroup $W' = \langle s_{\alpha}, s_{\beta} \rangle$ generated by s_{α}, s_{β} is a finite reflection group of rank 2. Let us consider the various such subgroups for the symmetric group \mathfrak{S}_n . A normal for the hyperplane $H_{i,j}$ for $1 \leq i < j \leq n$ is given by $\alpha_{i,j} := e_j - e_i$. Thus, for two distinct transpositions (i, j), (k, l), we have $\alpha_{i,j} \perp \alpha_{k,l}$ iff $\{i, j\} \cap \{k, l\} = \emptyset$. Otherwise

 $|\{i, j\} \cap \{k, l\}| = 1$ and the angle between $H_{(i,j)}$ and $H_{(k,l)}$ is $\frac{\pi}{3}$. In particular, \mathfrak{S}_3 is the symmetry group of the regular triangle embedded in \mathbb{R}^3 with vertices (1, 0, 0), (0, 1, 0), and (0, 0, 1).

The symmetric group \mathfrak{S}_n fixes the linear subspace $\{(t, t, \ldots, t) : t \in \mathbb{R}\}$ pointwise and is of rank n-1. In light of the classification of finite reflection groups that we will be seeing in a few lectures, let us start by calling \mathfrak{S}_n a reflection group of **type** A_{n-1} .

We close this first lecture with introducing one more example. For i = 1, ..., n, let $z_i : \mathbb{R}^n \to \mathbb{R}^n$ be reflection in the hyperplane $H_i = \{v \in \mathbb{R}^n : v_i = 0\}$. That is, z_i flips the sign of the *i*-th coordinate of *v*. Consider the group *W* that is generated by $s_{(i,j)}$ for $1 \le i < j \le n$ as well as $z_1, ..., z_n$. This is a group generated by reflections but it's not obvious that *W* is finite. To see that *W* is finite, consider the set $S = \{-1, +1\}^n$ of ± 1 -vectors of length *n*. The subgroup $G \subseteq \operatorname{GL}(\mathbb{R}^n)$ of linear symmetries of *S* is finite (why??) and *W* is clearly a subgroup. That makes *W* finite as well.

Exercise 2.3. Let $S \subset \mathbb{R}^n$ a finite set such that $\operatorname{span}(S) = \mathbb{R}^n$. Let G be the group of linear transformations $g \in \operatorname{GL}(\mathbb{R}^n)$ such that gS = S. Show that G is a finite group.

Note that W contains more reflections then the ones we used to generate. Indeed, $z_i s_{(i,j)} z_i$ maps e_i to $-e_j$ and e_j to $-e_i$ and leaves e_k fixed for $k \notin \{i, j\}$. But this means it fixes all points of the hyperplane $H = \{v \in \mathbb{R}^n : v_i = -v_j\}$ and maps its normal $e_i + e_j$ to its negative. The finite reflection group W is of rank n and we say that it is of type \mathbf{B}_n .

Exercise 2.4. Show that the reflection group of type B_n is the symmetry group of the *n*-dimensional cube $C_n = \{v \in \mathbb{R}^n : |v_i| \le 1 \text{ for all } i = 1, ..., n\}.$

Exercise 2.5. A convex polytope P in \mathbb{R}^3 is the inclusion-minimal convex set containing a given finite set of points. The symmetry group G of P is the group of linear transformations $g \in GL(\mathbb{R}^3)$ such that gP = P.

The boundary of P consists of vertices, edges, and faces. A **flag** of P is a choice of a vertex v, an edge e, and a face F such that $v \in e \subset F$. A convex polytope P is called **regular** if for two flags $v \in e \subset F$ and $v' \in e' \subset F'$ there is $g \in G$ such that gv = v', ge = e', and gF = F'. Show that if P is regular, then G is a finite reflection group.

Exercise 2.6. Consider two infinitely long walls meeting in a corner at an angle $\alpha \in (0, \pi]$. Show that any kicked ball (which doesn't loose momentum) can meet the walls only a finite number of times. What is the maximal number of times a ball can hit the walls?

3. Root systems

Let W be a finite reflection group acting on V and let $\mathcal{A}(W)$ be the collection of reflecting hyperplanes of W. If $H_{\alpha} \in \mathcal{A}(W)$ and $w \in O(V)$, then $ws_{\alpha}w^{-1}$ sends $w\alpha$ to its negative and pointwise fixes $wH_{\alpha} = \{v \in V : \langle \alpha, w^{-1}v \rangle = \langle w\alpha, v \rangle = 0\} = H_{w\alpha}$. Here we used the fact that $w \in O(V)$ and hence $w^* = w^{-1}$. If $w \in W$, then $ws_{\alpha}w^{-1} \in W$, we infer that $H_{w\alpha} \in \mathcal{A}(W)$. Hence $w\mathcal{A}(W) = \mathcal{A}(W)$ for all $w \in W$. Instead of the action of W on the reflection hyperplanes, it is customary to consider the action on a collection of normal vectors to the reflection hyperplanes. Since $s_{\alpha}(\alpha) = -\alpha$ it is not sufficient to pick a normal vector for each hyperplane.

A root system Φ is a finite non-empty subset of $V \setminus 0$ such that for every $\alpha \in \Phi$

(R1) $\Phi \cap \operatorname{span}(\alpha) = \{-\alpha, \alpha\}$, and (R2) $s_{\alpha}(\beta) \in \Phi$ for all $\beta \in \Phi$.

The elements of Φ are called **roots**. The **rank** of Φ is the dimension of span(Φ).

Every finite reflection group W gives rise to a (actually many) root system:

$$\Phi = \{ \alpha \in V : \langle \alpha, \alpha \rangle = 1, s_{\alpha} \in W \}$$

Conversely, if Φ is a root system, then define W as the subgroup of O(V) generated by the reflections $\{s_{\alpha} : \alpha \in \Phi\}$. We may assume that $V = \operatorname{span}(\Phi)$ and appealing to Exercise 2.5 shows that W is a finite group.

Clearly if Φ is a root system, then $t\Phi = \{t\alpha : \alpha \in \Phi\}$ is a root system as well for all $t \in \mathbb{R} \setminus 0$. We call Φ **reducible** if there is a partition $\Phi = \Phi' \uplus \Phi''$ such that $\Phi' \perp \Phi''$ and Φ' and Φ'' are root systems. If no partition exists, then Φ is **irreducible**.

Exercise 3.1. Let Φ be a root system. For any non-empty $U \subseteq \Phi$, show that $\Phi \cap \operatorname{span}(U)$ is a root system.

Exercise 3.2. Let Φ be an irreducible root system. Show that there are at most two different lengths of roots. (Hint: Show this first for root systems of rank 2.)

Example 3.3 (A root system for type A_{n-1} and type B_n). For type A_{n-1} : The set $\Phi = \{e_i - e_j : i, j \in [n], i \neq j\}$ is a root system for the symmetric group and since \mathfrak{S}_n acts transitively on Φ , Φ is unique up to scaling.

For type B_n : The set $\Phi = \{\pm (e_i - e_j), \pm (e_i + e_j) : 1 \le i < j \le n\} \cup \{\pm e_1, \ldots, \pm e_n\}$ is a root system whose associated reflection group is that of type B_n (check this!). Note that the roots have lengths 1 and $\sqrt{2}$. Since W acts by orthogonal transformations, there is more than one orbit of Φ under W.

We call $c \in V$ generic relative to Φ if $\langle c, \alpha \rangle \neq 0$ for all $\alpha \in \Phi$. Since Φ is finite, generic c's exist.

Exercise 3.4. Identifying $V = \mathbb{R}^n$, show that there are infinitely many $t \in \mathbb{R}$ such that $c = (1, t, t^2, \dots, t^n)$ is generic for Φ .

A positive system of Φ is a subset $\Phi^+ \subset \Phi$ of the form

$$\Phi^+ = \{ \alpha \in \Phi : \langle c, \alpha \rangle > 0 \}$$

for some generic c.

Clearly $|\Phi^+| = \frac{1}{2}|\Phi|$, as Φ^+ selects one element from each pair $-\alpha, \alpha \in \Phi$. But our choice serves a greater purpose. We seek to find smallest sets of reflections that generate W. As it will turn out, these subsets will be as small as possible.

Example 3.5 (Positive systems for type A_{n-1} and B_n). For type A_{n-1} : A vector c is generic relative to $\Phi = \{e_i - e_j : i, j \in [n], i \neq j\}$ if and only if $c_i \neq c_j$ for all $i \neq j$. Consider $c = (c_1 < c_2 < \cdots < c_n)$. Then $\Phi^+ = \{e_j - e_i : 1 \leq i < j \leq n\}$.

For type B_n : c is generic if $|c_i| \neq |c_j$ for all $i \neq j$ and $c_i \neq 0$ for all i. For $c = (0 < c_1 < \cdots < c_n)$, the positive system is $\Phi^+ = \{e_j - e_i, e_i + e_j : i < j\} \cup \{e_1, \dots, e_n\}$.

For a finite set $U = \{u_1, \ldots, u_m\} \subset V$, we define the **conical hull** as the set

cone(U) = {
$$\mu_1 u_1 + \mu_2 u_2 + \dots + \mu_m u_m : \mu_1, \dots, \mu_m \ge 0$$
}.

We call a finite set $U \subset V$ acyclic if there is $c \in V$ with $\langle c, u \rangle > 0$ for all $u \in U$.

THEOREM 3.6. Let $U \subset V$ be acyclic. If $U \cap \text{span}(u) = \{u\}$ for all $u \in U$, then there is a unique inclusion-minimal $G \subseteq U$ with cone(G) = cone(U).

PROOF. Let $G = \{g_1, \ldots, g_k\} \subset U$ be an inclusion-minimal generating set for $C := \operatorname{cone}(U)$. That is, $C = \operatorname{cone}(G)$ but $C \neq \operatorname{cone}(G \setminus g_j)$ for all $j = 1, \ldots, k$. Assume that $H = \{h_1, \ldots, h_l\} \subset U$ also generates C but, say, $g_1 \notin H$. Then there are $a_1, \ldots, a_l \geq 0$ such that $g_1 = \sum_i a_i h_i$ at least two a_i nonzero. On the other hand, there are $b_{ij} \geq 0$ such that $h_i = \sum_j b_{ij}g_j$. Setting $d_j = \sum_i a_i b_{ij} \geq 0$, we get

$$g_1 = d_1g_1 + d_2g_2 + \dots + d_kg_k$$

Said differently, $(1-d_1)g_1$ is contained in cone $(G \setminus g_1)$. We cannot have $1-d_1 > 0$, as this would contradict the assumption that G is inclusion-minimal. If $1-d_1 < 0$, then

$$0 > (1-d_1)\langle c, g_1 \rangle = \sum_{i=2}^k d_i \langle c, g_i \rangle \ge 0.$$

This leaves $d_1 = 1$. But the same calculation then shows $d_2 = \cdots = d_k = 0$, which implies $g_1 \in S$. Hence $G \subseteq U$.

By Theorem 3.6, there is a unique inclusion-minimal subset $\Delta \subseteq \Phi^+$ that minimally generates cone (Φ^+) . We call Δ a **simple system**. Figure 2 shows two examples of root systems, positive systems, and simple systems in rank 2.



FIGURE 2. Two examples of finite reflection groups in the plane. Below root systems are shown. The positive system is opaque. The simple roots are slightly thicker.

We start with a seemingly technical but important lemma about simple systems.

Lemma 3.7. Let Δ be a simple system. Then $\langle \alpha, \beta \rangle \leq 0$ for all $\alpha, \beta \in \Delta, \alpha \neq \beta$.

PROOF. Let $\alpha, \beta \in \Delta$ with $\alpha \neq \beta$. Then $L = \operatorname{span}(\alpha, \beta)$ is a 2-dimensional subspace and Exercise 3.1 yields that $\Phi \cap L$ is a root system with positive system $\Phi^+ \cap L$. Let $\Delta' \subseteq \Phi^+ \cap L$ be a simple system. If $\alpha \notin \Delta'$, then $\Delta' \cup (\Delta \setminus \alpha)$ generates cone (Φ^+) , contradicting Theorem 3.6. Hence $\alpha, \beta \in \Delta'$ and, using that L is 2-dimensional, $\Delta' = \{\alpha, \beta\}$. In particular, α, β are linearly independent.

Now assume that $\langle \alpha, \beta \rangle > 0$. We know that $\gamma = s_{\alpha}(\beta)$ is contained in $\Phi \cap L$. Now $s_{\alpha}(\beta) = \beta + \mu \alpha$, where $\mu = \frac{-2\langle \alpha, \beta \rangle}{\langle \alpha, \alpha \rangle} < 0$. But γ or $-\gamma$ is contained in $\Phi^+ \cap L$ but the unique expression of γ as a linear combination of α and β has positive and negative coefficients. This contradicts that $\Phi^+ \cap L \subseteq \operatorname{cone}(\alpha, \beta)$.

A main consequence of this is the following.

Corollary 3.8. Let Δ be a simple system, then Δ is linear independent. In particular, every root $\alpha \in \Phi$ has a unique expression in terms of simple roots, with all coefficients nonnegative or nonpositive.

PROOF. Let $\alpha_1, \ldots, \alpha_m \in \Delta$ be a minimally dependent subset. Then there are $a_1, \ldots, a_m \in \mathbb{R}$ not all zero such that $0 = \sum_i a_i \alpha_i$. Since $\langle c, \alpha_i \rangle > 0$ for some generic c that brought us Φ^+ , not all a_i are of the same sign. We may assume that $a_1, \ldots, a_k < 0 < a_{k+1}, \ldots, a_m$. Then

$$-\sum_{i=1}^k a_i \alpha_i = \sum_{j=k+1}^m a_j \alpha_j =: v$$

and minimality yields $v \neq 0$. We compute

$$0 < \langle v, v \rangle = \sum_{i=1}^{k} \sum_{j=k+1}^{m} (-\alpha_i) \alpha_j \langle \alpha_i, \alpha_j \rangle \leq 0,$$

which is a contradiction.

The corollary furnishes another characterization of simple systems.

Corollary 3.9. Let $S \subseteq \Phi$ be a basis for span (Φ) such that $\Phi \subset \operatorname{cone}(S) \cup \operatorname{cone}(-S)$, then S is a simple system.

PROOF. We may assume that $\operatorname{span}(\Phi) = V$. Then $S = \{\alpha_1, \ldots, \alpha_n\}$ is a basis and there is some $c \in V$ with $\langle c, \alpha_i \rangle > 0$ for all *i*. As every $\beta \in \Phi$ is of the form $\beta = \sum_i a_i \alpha_i$ for some α_i that are all nonnegative or nonpositive, this shows that *c* is generic. In particular $\beta \in \Phi^+$ if and only if $\beta \in \operatorname{cone}(S) \cap \Phi$, which shows that *S* is a simple system.

Example 3.10 (Simple systems for types A_{n-1} and B_n). Continuing Example 3.5, let us choose $c = (0 < c_1 < \cdots < c_n)$, then the positive system for type A_{n-1} is $\Delta = \{e_2 - e_1, e_3 - e_2, \ldots, e_n - e_{n-1}\}$. Indeed, for any $e_j - e_i \in \Phi^+$ with $1 \le i < j \le n$ we have

$$e_j - e_i = (e_j - e_{j-1}) + (e_{j-1} - e_{j-2}) + \dots + (e_{i+1} - e_i).$$

Likewise, for type B_n , we obtain $\Delta = \{e_1, e_2 - e_1, e_3 - e_2, \dots, e_n - e_{n-1}\}$. In addition to the positive roots $e_j - e_i$ for i < j, we get e_1 and $e_j = e_j - e_{j-1} + e_{j-1}$ by induction on j. The positive roots $e_j + e_i$ are then obvious.

The fact that every root has a unique representation in terms of Δ with nonzero coefficients of like sign is the key in showing that Δ yields a generating set for W.

Lemma 3.11. Let $\Delta \subseteq \Phi^+ \subseteq \Phi$. For $\alpha \in \Delta$ and $\beta \in \Phi^+$, we have $s_{\alpha}(\beta) \in \Phi^+$ if $\beta \neq \alpha$ and $s_{\alpha}(\beta) = -\alpha$ otherwise.

PROOF. Let $\Delta = \{\alpha_1, \ldots, \alpha_n\}$, $\alpha = \alpha_1$, and $\beta = \sum_i a_i \alpha_i$ with $a_1, \ldots, a_n \ge 0$. If $\alpha \ne \beta$, then there is some $a_i > 0$ for $i \ge 2$. Now

$$s_{\alpha}(\beta) = \beta - \mu \alpha_1 = (a_1 - \mu)\alpha_1 + \sum_{i \ge 2} a_i \alpha_i \,.$$

Since $s_{\alpha}(\beta) \in \Phi$ and the expression of $s_{\alpha}(\beta)$ is unique with nonzero coefficients of like sign, the fact that $\alpha_i > 0$, forces $a_1 - \mu$ to be positive as well.

THEOREM 3.12. Let W be a finite reflection group with root system Φ . Let $\Delta \subset \Phi$ be a simple system, then $\{s_{\alpha} : \alpha \in \Delta\}$ generates W

PROOF. Let W' be the subgroup of W generated by the reflections $\{s_{\alpha} : \alpha \in \Delta\}$. It suffices to show that for every $\beta \in \Phi^+$, there is $w \in W'$ such that $w\beta \in \Delta$. Indeed if $\beta = w^{-1}\alpha$ for $w \in W'$ and $\alpha \in \Delta$, then $s_{\beta} = s_{w^{-1}\alpha} = w^{-1}s_{\alpha}w$ and hence $s_{\beta} \in W'$.

For any $\gamma \in \Phi^+$ let $\gamma = \sum_{\alpha \in \Delta} c_{\alpha} \alpha$ be the unique representation with all $c_{\alpha} \ge 0$ and define the **height** as $ht(\beta) = \sum_{\alpha \in \Delta} c_{\alpha}$. Pick $\gamma \in W'\beta \cap \Phi^+$ with $ht(\gamma)$ minimal. We claim that $\gamma \in \Delta$. Since $\gamma \ne 0$, we have

$$0 < \langle \gamma, \gamma \rangle = \sum_{\alpha \in \Delta} c_{\alpha} \langle \gamma, \alpha \rangle$$

and thus there is some $\alpha \in \Delta$ with $c_{\alpha} > 0$ and $\langle \gamma, \alpha \rangle > 0$. But by (1), $s_{\alpha}(\gamma) = \gamma - \mu \alpha$, where $\mu > 0$. If $s_{\alpha}(\gamma)$ is in Φ^+ , then $\operatorname{ht}(s_{\alpha}(\gamma)) < \operatorname{ht}(\gamma)$, which would contradict our choice of γ . Hence $s_{\alpha}(\gamma) \in -\Phi^+$ and by Lemma 3.11, this implies $\gamma = \alpha$.

Example 3.13 (Generation by simple reflections in types A_{n-1} and B_n). Continuing Example 3.10, note that $ht(e_j - e_i) = j - i$. Applying, for example, s_α for $\alpha = e_j - e_{j-1}$ or $\alpha = e_{i+1} - e_i$ maps $e_j - e_i$ to $e_{j-1} - e_i$ or $e_j - e_{i+1}$, both of which have lower height. Repeating this, the process terminates at some $e_k - e_{k-1}$. Notice that the root of minimal height in $W'\beta$ is not unique.

Let us write $s_{j,i}$ for $s_{e_j-e_i}$ and $s_i = s_{i+1,i}$. Then $s_{i+1} \cdots s_{j-1}(e_j - e_i) = e_{i+1} - e_i$ and we obtain

$$s_{e_j-e_i} = s_{j-1}\cdots s_{i+1}s_is_{i+1}\cdots s_{j-1}$$

For example, for $e_3 - e_1$, we get $s_2(e_3 - e_1) = e_2 - e_1$ and $s_{3,1} = s_2 s_1 s_2$.

Exercise 3.14. Let $\Phi = \{e_i - e_j : i \neq j\}$ be the root system of type A_{n-1} . Every subsets $U \subseteq \Phi$ determines a directed graph D = (V, A) on nodes $V = \{1, \ldots, n\}$ and arcs $A = \{(i, j) : e_i - e_j \in U\}$.

- (1) Show that U generates \mathfrak{S}_n if and only if D is connected.
- (2) Show that any minimal generating set U has the same cardinality.
- (3) How many minimal generating sets U are there?
- (4) How many simple systems are contained in Φ ?

Exercise 3.15. Exercise 3.14 suggests that U minimally generates \mathfrak{S}_n if and only if U is a basis for $\{v \in V : v_1 + \cdots + v_n = 0\}$. Show that \mathfrak{S}_n is special in that respect.

4. Reflection arrangements and the length function

Let us interpret what we did geometrically. Let W be a finite reflection group with an arbitrary but fixed root system Φ . Recall that the reflection arrangement associated to W is the collection of hyperplanes $\mathcal{A}(W) = \{H_{\alpha} : \alpha \in \Phi\}$. A vector $c \in V$ is generic if and only if c is not contained in any of the hyperplanes in $\mathcal{A}(W)$. Let Φ_0^+ be an arbitrary but fixed positive system. For $c \in V \setminus 0$, we write $H_c^{\geq} := \{v : \langle c, v \rangle \geq 0\}$ for the **positive halfspace** that is bounded by the hyperplane H_c and $H_c^{\geq} := H_c^{\geq} \setminus H_c$ for the **open** halfspace. Now $c \in V \setminus 0$ yields Φ_0^+ if and only if $\Phi_0^+ = \Phi \cap H_c^>$, that is, $\langle \alpha, c \rangle > 0$ for all $\alpha \in \Phi_0^+$. More generally, for $v \notin \bigcup \mathcal{A}(W)$, let $\sigma_{\alpha} = \operatorname{sgn}\langle \alpha, v \rangle \in \{-1, +1\}$ for all $\alpha \in \Phi_0^+$. Then the connected component of $V \setminus \bigcup \mathcal{A}(W)$ containing v is

$$C^{\circ}_{\sigma} := \{ v \in V : \langle \sigma_{\alpha} \alpha, v \rangle > 0 \text{ for all } \alpha \in \Phi^+_0 \}$$

and yields the positive system $\{\sigma_{\alpha}\alpha : \alpha \in \Phi_0^+\}$. Thus, the connected components of

$$V \setminus \bigcup \mathcal{A}(W)$$

are in bijection to the positive (and hence simple) systems of W. We write C_{σ} for the topological closure of C_{σ}° . Since C_{σ}° is non-empty, we get

$$C_{\sigma} = \{ v \in V : \langle \sigma_{\alpha} \alpha, v \rangle \ge 0 \text{ for all } \alpha \in \Phi_0^+ \}$$

The closures of the various connected components are called the **regions** or **chambers** of $\mathcal{A}(W)$, which we collect in $\mathcal{R}(W)$.

A set $C \subseteq V$ is a **polyhedral cone** if there are $\beta_1, \ldots, \beta_m \in V$ with

$$C = \{ v : \langle \beta_i, v \rangle \ge 0 \text{ for all } i = 1, \dots, m \} = H_{\beta_1}^{\ge} \cap H_{\beta_2}^{\ge} \cap \dots \cap H_{\beta_m}^{\ge}.$$

The choice of β_i is not unique. Indeed, for $\mu_1, \ldots, \mu_m \ge 0$ define $\beta = \mu_1 \beta_1 + \cdots + \mu_m \beta_m$. Then $\langle \beta, v \rangle \ge 0$ for all $v \in C$ and $C = C \cap H_{\beta}^{\ge}$. We call the cone C simplicial if there is a choice of linearly independent β_1, \ldots, β_m . It is easy to see that C is then linearly isomorphic to $\mathbb{R}^m_{\ge 0} \times \mathbb{R}^{n-m}$ if $n = \dim V$. We call an arrangement of hyperplanes simplicial if all regions are simplicial.

Corollary 4.1. For any finite reflection group W, the arrangement $\mathcal{A}(W)$ is simplicial.

PROOF. Let Φ^+ be a positive system with associated chamber $C = \{v : \langle \beta, v \rangle \ge 0 \text{ for all } \beta \in \Phi^+\}$. Let $\Delta = \{\alpha_1, \ldots, \alpha_n\} \subseteq \Phi^+$ be the simple system. We claim that

$$C = \{ v : \langle \alpha, v \rangle \ge 0 \text{ for all } \alpha \in \Delta \},\$$

•

 \diamond

which then yields the result using Corollary 3.8. Let C' be the right-hand side. Since $\Delta \subseteq \Phi^+$, we get $C \subseteq C'$. Now for any $\beta \in \Phi^+$, there are $b_1, \ldots, b_n \ge 0$ such that $\beta = b_1\alpha_1 + \cdots + b_n\alpha_n$. If $c \in C'$, then $\langle \beta, c \rangle = b_1 \langle \alpha_1, c \rangle + \cdots + b_n \langle \alpha_n, c \rangle \ge 0$, which shows $c \in C$.

Example 4.2 (Regions of types A_{n-1} and B_n). We already did most of the leg work at the end of Section 1. The chambers of type A_{n-1} are the cones

$$\{ v \in \mathbb{R}^n : v_{\tau(1)} < v_{\tau(2)} < \dots < v_{\tau(n)} \}$$

as τ varies over all permutations $\tau \in \mathfrak{S}_n$. Each cone is linearly isomorphic to $\mathbb{R}^{n-1}_{\geq 0} \times \mathbb{R}$. In type B_n , the simple systems in Example 3.10 shows that the regions are of the form

$$\{v \in \mathbb{R}^n : 0 < \rho_1 v_{\tau(1)} < \rho_2 v_{\tau(2)} < \dots < \rho_n v_{\tau(n)}\}\$$

as τ varies over all permutations $\tau \in \mathfrak{S}_n$ and $\rho_1, \ldots, \rho_n \in \{-1, +1\}^n$.

The group W acts on the set of regions $\mathcal{R}(W)$. For every $w \in W$, $w\Phi_0^+$ is also a positive system as $w\Phi_0^+ = \Phi \cap H_{wc}^>$. Likewise, if $\Delta_0 \subseteq \Phi_0^+$ is the associated simple system, then $w\Delta_0$ is a simple system for all $w \in W$. The next thing that we want to verify is that every positive (and hence simple) system is of the form $w\Phi_0^+$ for some $w \in W$. Stronger even, we want to show that W acts **simply transitive** on the chambers of $\mathcal{A}(W)$, that is:

THEOREM 4.3. Let Φ^+ be a positive system. Then there is a unique $w \in W$ with $\Phi^+ = w\Phi_0^+$.

Let $C \in \mathcal{R}(W)$ be a chamber. A hyperplane $H \in \mathcal{A}(W)$ is a wall of C if $\operatorname{span}(C \cap H) = H$. If $C = H_{\beta_1}^{\geq} \cap \cdots \cap H_{\beta_m}^{\geq}$ is simplicial and β_1, \ldots, β_m linearly independent, then H_{β_i} is a wall of C for each $i = 1, \ldots, m$.

If H is a wall, then $F = C \cap H$ is a **facet** (or **panel**) of C. For every facet F of C there is a unique chamber $C' \in \mathcal{R}(W)$ with $F = C \cap C'$. We call C and C' **adjacent**. A hyperplane $H \in \mathcal{A}(W)$ **separates** a chamber C from C' if C and C' lie on different sides of H. If C, C' are adjacent, then $\operatorname{span}(C \cap C')$ is the unique hyperplane that separates C from C'. We call C_1, C_2, \ldots, C_k of distinct chambers a **gallery** if C_i, C_{i+1} are adjacent for $1 \leq i < k$.

Proposition 4.4. Let C, C' be regions of the reflection arrangement $\mathcal{A}(W)$. If C, C' are adjacent with separating hyperplane $H_{\alpha} \in \mathcal{A}(W)$. Then $s_{\alpha}(C) = C'$.

PROOF. W acts on $\mathcal{A}(W)$ and hence on the regions $\mathcal{R}(W)$. In particular s_{α} fixes the facet $C \cap C' \subset H_{\alpha}$ pointwise. As s_{α} exchanges $H_{\alpha}^{<}$ and $H_{\alpha}^{>}$, this proves the claim.

PROOF OF THEOREM 4.3 – EXISTENCE. Let C_0 and C be the chambers corresponding to the positive systems Φ_0^+ and Φ^+ , respectively. Pick points $p \in C_0^\circ$, $q \in C^\circ$ such that the segment $[p,q] = \{p + \lambda(q-p) : 0 \le \lambda \le 1\}$ does not meet any of the finitely many codimension-2 subspace $H \cap H'$ for $H, H' \in \mathcal{A}(W)$ and $H \ne H'$. Let $H_{\beta_1}, H_{\beta_2}, \ldots, H_{\beta_k} \in \mathcal{A}(W)$ be the ordered sequence of hyperplanes that meet the segment [p,q] in distinct points. This means that there are chambers $C_0, C_1, \ldots, C_k = C$ that meet [p,q] such that $C_i C_{i-1}$ are adjacent and separated by H_{β_i} for $i = 1, \ldots, k$. It follows from Proposition 4.4 that $C_i = s_{\beta_i}(C_{i-1})$ for $i = 1, \ldots, k$ and hence $C = wC_0$ for $w = s_{\beta_k} \cdots s_{\beta_1}$; see Figure 3. On the level of positive systems, this means $\Phi^+ = w\Phi_0^+$.

 \diamond



FIGURE 3. Illustration for proof of Theorem 4.3.

This proof paints a very geometric picture that we can also use to give an alternative proof of Theorem 3.12.

GEOMETRIC PROOF OF THEOREM 3.12. It suffices to show that every s_{β} for $\beta \in \Phi^+$ can be written as a product of simple reflections. As before let C_0 be the chamber corresponding to Δ_0 and pick points $p \in C_0^\circ$ and $q \in H_\beta$ such that the segment misses the finitely many codimension-2 intersections of hyperplanes in $\mathcal{A}(W)$. We again obtain a sequence of chambers C_0, C_1, \ldots, C_k such that H_β is a wall for C_k (but for none of the other chambers). If k = 0, then H_β is a wall of C_0 and hence $\beta \in \Delta_0$ and s_β is a simple reflection.

If k > 0, then let H_{β_i} be the hyperplane separating C_{i-1} from C_i and set $\beta_{k+1} = \beta$. Moreover, let $t_i = s_{\beta_i}$ be the reflection in H_{β_i} . Note that t_1 is a simple reflection, that $C_{i-1} = t_i(C_i)$ and hence $t_1 \cdots t_{i-1}(H_{\beta_i})$ is a wall of C_0 . It follows that $s_i = t_1 t_2 \cdots t_{i-1} t_i t_{i-1} \cdots t_2 t_1$ is a simple reflection. By induction, we get that $t_i = t_{i-1} \cdots t_2 t_1 s_i t_1 t_2 \cdots t_{i-1}$ is a product of simple reflections.

Let us harvest this geometric perspective further!

Construction 4.5. If $w = s_1 s_2 \cdots s_r$ for simple reflections $s_i = s_{\alpha_i}$, then define

$$t_{1} := s_{1}$$

$$t_{2} := s_{1} s_{2} s_{1}$$

$$\vdots$$

$$t_{r} := s_{1} s_{2} \cdots s_{r-1} s_{r} s_{r-1} \cdots s_{2} s_{1}.$$

Then each t_i is a reflection in the hyperplane H_{β_i} with $\beta_i = s_1 \cdots s_{i-1} \alpha_i$. Moreover

 $t_k t_{k-1} \cdots t_1 = s_1 s_2 \cdots s_k$

for all k = 1, ..., r. Most importantly, if we define

$$C_k := t_k(C_{k-1}) = t_k t_{k-1} \cdots t_1 C_0 = s_1 s_2 \cdots s_k C_0$$

for k = 1, ..., r, then $C_0, ..., C_r = wC$ is a gallery and t_i is the reflection in the unique hyperplane separating C_{i-1} and C_i .

As before let C_0 be the chamber corresponding to Φ_0^+ . Note that $C_0 \subseteq H_\beta^{\geq}$ for all $\beta \in \Phi_0^+$. For every chamber C, let us write $\Phi_0^+(C) = \{\beta \in \Phi^+ : C \subseteq H_\beta^{\leq}\}$. That is, $\Phi_0^+(C)$ records the hyperplanes separating C from C_0 . Moreover,

$$C = \bigcap_{\alpha \in \Phi_0^+(C)} H_{\alpha}^{\leq} \cap \bigcap_{\alpha \in \Phi_0^+ \setminus \Phi_0^+(C)} H_{\alpha}^{\geq}$$

If C corresponds to the positive system Φ^+ , then $\Phi_0^+(C) = \Phi_0^+ \cap -\Phi^+$. We write $n(C) := |\Phi_0^+(C)|$ as the number of hyperplanes separating C from C_0 .

Exercise 4.6. Let \mathcal{A} be a collection of finitely many hyperplanes in V and $\mathcal{R} = \mathcal{R}(\mathcal{A})$ its set of regions. For any two regions $C, C' \in \mathcal{R}$ write n(C,C') for the number of hyperplanes separating C from C'.

- (1) Show that n defines a metric on \mathcal{R} .
- (2) Let $p \in C^{\circ}$ and $q \in (C')^{\circ}$ be generic. Show that n(C, C') is the number of hyperplanes $H \in \mathcal{A}$ that meet [p, q].
- (3) Let $C = C_0, C_1, \ldots, C_k = C'$ be a gallery and $H_i = \operatorname{span}(C_{i-1} \cap C_i)$ the walls along the gallery. Show that if k > n(C, C'), then there are i < j such that $H_i = H_j$.

Let C_0 be the chamber for Φ_0^+ and $w \in W$. We define $\Phi_0^+(w) := \Phi_0^+(wC_0)$ and $n(w) := n(wC_0)$.

Lemma 4.7. Let $w = s_1 \cdots s_r$ such that n(w) < r, then there are i < j such that

$$w = s_1 \cdots \widehat{s_i} \cdots \widehat{s_j} \cdots s_r,$$

where \hat{s}_i and \hat{s}_j stands for omission.

PROOF. Consider the gallery C_0, \ldots, C_r of Construction 4.5 for $w = s_1 \cdots s_r$. If r > n(w), then the gallery traverses a hyperplane twice by Exercise 4.6. That is, $t_i = t_j$ for some i < j but this means

$$s_1 \cdots s_{i-1} s_i s_{i-1} \cdots s_1 = s_1 \cdots s_{i-1} s_i s_{i+1} \cdots s_{j-1} s_j s_{j-1} \cdots s_{i+1} s_i s_{i-1} \cdots s_1,$$

which reduces to

$$s_1 \cdots s_{i-1} = s_1 \cdots s_{i-1} s_i s_{i+1} \cdots s_{j-1} s_j s_{j-1} \cdots s_{i+1},$$

which reduces to

$$s_1 \cdots s_{i-1} s_{i+1} \cdots s_{j-1} = s_1 \cdots s_{i-1} s_i s_{i+1} \cdots s_{j-1} s_j.$$

By Theorem 3.12 for every $w \in W$ there are $\alpha_1, \ldots, \alpha_k \in \Delta_0$ such that $w = s_{\alpha_1} \cdots s_{\alpha_k}$. If k is minimal, then we call $s_{\alpha_1} \cdots s_{\alpha_k}$ a **reduced expression** for w and define the **length** of w (relative to Δ_0) as $\ell(w) := k$.

Proposition 4.8. Let $w \in W$.

- (i) $\ell(e) = 0$ and $\ell(w) = 1$ if and only if $w = s_{\alpha}$ for some $\alpha \in \Delta_0$.
- (ii) $\ell(w) = \ell(w^{-1}).$
- (iii) $\ell(ww') \le \ell(w) + \ell(w')$.
- (iv) $\ell(s_{\alpha}w) = \ell(ws_{\alpha}) = \ell(w) \pm 1$ for all $\alpha \in \Delta_0$.

PROOF. (i) is clear. For (ii): If $w = s_{\alpha_1} \cdots s_{\alpha_k}$, then $w^{-1} = s_{\alpha_k} \cdots s_{\alpha_1}$, which shows $\ell(w^{-1}) \leq \ell(w)$. Since $w = (w^{-1})^{-1}$, we also get $\ell(w) \leq \ell(w^{-1})$. For (iii) just compose reduced expressions for w and w'.

For (iv), first note that $|\ell(s_{\alpha}w) - \ell(w)| \leq 1$. Now $\det(s_a) = -1$ (as H_{α} is the eigenspace to the eigenvalue 1 and $(H_{\alpha})^{\perp} = \mathbb{R}\alpha$ is the eigenspace to eigenvalue -1). Thus $\det(w) = (-1)^{\ell(w)}$. This implies $\ell(s_{\alpha}w) \neq \ell(w)$.

The next theorem gives a geometric interpretation of the length function.

THEOREM 4.9. Let W be a finite reflection group with simple positive systems $\Delta_0 \subseteq \Phi_0^+$. For all $w \in W$, we have $\ell(w) = n(w) = |\Phi_0^+ \cap w^{-1}(-\Phi_0^+)|$.

PROOF. Let $w = s_1 s_2 \cdots s_r$ be a reduced expression with simple reflections s_1, \ldots, s_r . Then there are at most r distinct hyperplanes in the gallery of Construction 4.5 that separate C_0 from $C_r = wC_0$. By Exercise 4.6, we obtain $n(w) = n(wC_0) \leq r = \ell(w)$. However, if $n(wC_0) < r$, then Lemma 4.7 yields $w = s_1 \cdots \hat{s_i} \cdots \hat{s_j} \cdots s_r$ which contradicts the assumption that the expression was reduced.

PROOF OF THEOREM 4.3 – UNIQUENESS. Assume that there is $w \in W$ such that $w\Phi_0^+ = \Phi_0^+$. But this means that n(w) = 0 and by Theorem 4.9 we get w = e.

The following deletion condition follows directly from Theorem 4.9 and Lemma 4.7.

Corollary 4.10. Let $w \in W$ and s_{α} a simple reflection.

- (1) $\ell(ws_{\alpha}) = \ell(w) + 1$ if and only if $w\alpha \in \Phi_0^+$.
- (2) $\ell(ws_{\alpha}) = \ell(w) 1$ if and only if $w\alpha \in -\Phi_{0}^{+}$.
- (3) (Deletion Condition) Let $w = s_1 \cdots s_r$ be a product of simple reflections. If the expression is not reduced, then there exist indices $1 \le i < j \le r$ with $w = s_1 \cdots \widehat{s_i} \cdots \widehat{s_j} \cdots s_r$.
- (4) (Exchange Condition) Let $w = s_1 \cdots s_r$ be a product of simple reflections and s some simple reflection. If $\ell(ws) < \ell(w)$, then there is $1 \le i \le r$ with $w = s_1 \cdots \widehat{s_i} \cdots s_r s$. In particular, w has a reduced expression ending in s if and only if $\ell(ws) < \ell(w)$.

Exercise 4.11. Proof Corollary 4.10.

Exercise 4.12. Let W be a finite reflection group with simple system Δ and length function ℓ relative to Δ .

- (1) Show that there is a unique element $w_0 \in W$ of maximal length. This is called the **longest** element of W relative to Δ . What is the length?
- (2) Show that w_0 is an involution, that is $w_0^2 = e$.
- (3) Prove that in every reduced expression of w_0 , every simple reflection must occur at least once.
- (4) Let w with reduced expression $w = s_1 \cdots s_r$. Show that there is a w' with reduced expression $w' = s_{r+1} \cdots s_m$ such that $s_1 \cdots s_r s_{r+1} \cdots s_m$ is a reduced expression for w_0 .
- (5) Show that for every $w \in W$ there is a simple system Δ such that w is the longest element.

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5. Fundamental domains and parabolic subgroups

For a group G acting on a space V, a **fundamental domain** is a *nice* (e.g. connected) subset $D \subset V$ such that D meets every orbit Gv for $v \in V$ in a unique point. Fundamental domains for arbitrary group actions might be tricky. For example, if G acts on $V = \mathbb{R}^2$ by rotation of $\frac{\pi}{2}$, then a fundamental domain is given by

$$D = \{(0,0)\} \cup \{(x,0) : x > 0\} \cup \{(x,y) : x, y > 0\}$$

see Figure 4. This set is neither open nor closed and it can be shown(?) that there is no nice connected fundamental domain for this action. The situation for finite reflection groups is rather different. If, for example, $W = \{e, s_{\alpha}\}$, then H_{α}^{\geq} or H_{α}^{\leq} acts as a fundamental domain, which is as nice as possible (closed, convex).



FIGURE 4. Fundamental domain for a rotation group acting on the plane. The blue points are in one orbit. The reddish point, half line and positive orthant are a fundamental domain.

THEOREM 5.1. Let W be a finite reflection group. Then any $C \in \mathcal{R}(W)$ is a fundamental domain.

PROOF. Let $C_0 \in \mathcal{R}(W)$ be a chamber with simple system Δ_0 . For $v \in V$ we need to show that Wv meets C_0 in exactly one point. To see that there is $w \in W$ with $wv \in C_0$, let $C \in \mathcal{R}(W)$ with $v \in C$. By Theorem 4.3, there is a unique $w \in W$ with $C = wC_0$, that is, $C_0 = w^{-1}C$ and $w^{-1}v =: p \in C_0$.

Assume that there is $w' \in W$ with $w'v \in C_0$. This means that $p := w'v \in C_0$ and $wp =: q \in C_0$. If p is in the interior of C_0 , then so is q and $wC_0 = C_0$ but this can only happen for w = e. Thus, $p, q \in \partial C_0$. We wish to prove that p = q.



Let $C = wC_0$. We prove the claim by induction on $\ell(w)$, the number of hyperplanes separating C_0 from C. Observe that $C_0 \cap C \neq \emptyset$ as both contain q. We claim that there is a wall H_β of C that separates C_0 from C and $q \in C \cap H_\beta$. If not, then every wall H of C that contains q satisfies $C_0 \subseteq H^{\geq}$ but this is absurd!. Now $C' = s_\beta(C)$ also contains q and hence $s_\beta wp = q$ and $\ell(s_\beta w) < \ell(w)$. The result now follows by induction.

As an upshot of the proof, we can determine the **isotropy group** (or **stabilizer group**) $W_v := \{w \in W : wv = v\}$ for every point in V. For $v \in C_0$, the induction actually proves that if we let $J := \{\alpha \in \Delta_0 : v \in H_{\alpha_0}\}$, then W_v is generated by the reflections $\{s_\alpha : \alpha \in J\}$. Conversely for any $J \subseteq \Delta$, the subgroup $W_J = \langle s_\alpha : \alpha \in J \rangle$ is the isotropy group for all points in the linear subspace $L_J := \bigcap_{\alpha \in J} H_\alpha$. We call W_J a **standard parabolic subgroup** relative to the simple system Δ_0 . For any $w \in W$, we call wW_Jw^{-1} a **parabolic subgroup**. That is, W' is a parabolic subgroup if W' is a standard parabolic subgroup for some simple system Δ .

Since for any $v \in V$, there is $w \in W$ with $wv \in C_0$, we deduce.

Corollary 5.2. Every isotropy group is a parabolic subgroup.

Exercise 5.3. Find an example of a reflection group W and a subgroup $W' \subset W$ that is generated by reflections but that is not a parabolic subgroup.

We can make use of parabolic subgroups to study the length generating polynomial

$$W(q) = \sum_{w \in W} q^{\ell(w)}$$

Example 5.4 (Dihedral groups). For the dihedral group \mathcal{D}_m , we can compute by inspection

$$\mathcal{D}_m(q) = 1 + 2q + 2q^2 + \dots + 2q^{m-1} + q^m$$

Let us define $[n]_q := 1 + q + q^2 + \dots + q^{n-1}$, the *q*-integer. Then

$$\mathcal{D}_m(q) = (1+q)(1+q+q^2+\dots+q^{m-1}) = [2]_q[m]_q.$$

To be able to compute W(q), we want to use that for W_I , we can decompose W into cosets wW_I . If we can find suitable coset representative on which the length function is additive, then this might pave the way for an inductive procedure.

We defined W_I as the reflection group defined by a subset of simple reflections. It follows from Exercise 3.1 that $\Phi_I = \Phi \cap \text{span}(I)$ is a root system for W_I with simple system I. Relative to I, we can define a length function ℓ_I on W_I .

Proposition 5.5. We have $\ell_I(w) = \ell(w)$ for any $w \in W_I$.

PROOF. We recall that $\ell(w) = |\{\beta \in \Phi^+ : w\beta \in -\Phi^+\}|$. For $\beta \in \Phi^+ \setminus \Phi_I^+$ and $\beta = \sum_{\alpha \in \Delta} c_\alpha \alpha$ with $c_\alpha \ge 0$, there is some $\gamma \in \Delta \setminus I$ with $c_\gamma > 0$. Thus, for all $\alpha \in I$, the coefficient of γ of $s_\alpha(\beta)$ is still positive. Thus, for $w \in W_I$ and $\beta \in \Phi^+$, this means $w\beta \in -\Phi^+$ if and only if $\beta \in \Phi_I^+$. Hence $\ell_I(w) = \ell(w)$. \Box

For $I\subseteq \Delta$ define

$$W^I := \{ w \in W : \ell(ws_\alpha) > \ell(w) \text{ for all } \alpha \in I \}.$$

Lemma 5.6. For every $w \in W$ there is a unique $u \in W^I$ and $v \in W_I$ such that w = uv and $\ell(w) = \ell(u) + \ell(v)$.

PROOF. For $w \in W$, let $u \in wW_I$ with $\ell(u)$ minimal and write uv = w for $v \in W_I$. Let $u = s_1 \cdots s_k$ and $v = s_{k+1} \cdots s_{k+l}$ be reduced expressions. If $uv = s_1 \cdots s_k s_{k+1} \cdots s_{k+l}$ is not reduced, then by the Deletion Condition of Corollary 4.10 there are $1 \leq i < j \leq k+l$ such that s_i and s_j can be removed without altering uv. Now $j \leq k$ or k < i would contradict the reducedness of the expressions for u and v. Thus i < k < j, but then this means that $u' = s_1 \cdots \hat{s_i} \cdots s_k \in wW_I$ is of shorter length. Hence $\ell(w) = \ell(uv) = \ell(u) + \ell(v)$. If there is another $u' \in wW_I = uW_I$ with $\ell(u') = \ell(u)$, then u = u'v' for some $v' \in W_I$ and the same argument shows $\ell(u) = \ell(u') + \ell(v')$. But then $\ell(v') = 0$ and v' = e.

Since u is chosen of minimal length in wW_I , this implies $\ell(us) > \ell(u)$ for all $s \in I$ and hence $u \in W^I$. \Box

The elements in W^I are called **minimal coset representatives**. For $X \subseteq W$ we define $X(q) := \sum_{w \in X} q^{\ell(w)}$. Then Lemma 5.6 implies

Corollary 5.7. For any $J \subseteq \Delta$

$$W(q) = W^J(q)W_J(q).$$

Let us interpret W^I geometrically. Recall that $\ell(w^{-1}) = \ell(w)$ and $(ws_{\alpha})^{-1} = s_{\alpha}w^{-1}$. Hence, we can write

$$W^{I} := \{w^{-1} : \ell(s_{\alpha}w) > \ell(w)\}$$

The benefit of this small change is that according to Construction 4.5, $\ell(s_{\alpha}w) > \ell(w)$ if and only if wC_0 is not separated from C_0 by the hyperplane H_{α} . Hence W^I is in bijection to all chambers $C \in \mathcal{R}(W)$ with $C \subseteq \bigcap_{\alpha \in I} H_{\alpha}^{\geq}$. Let $\mathcal{R}(W)^I \subseteq \mathcal{R}(W)$ be the collection of all these chambers. The reflection arrangement $\mathcal{A}(W_I)$ is a subarrangement of $\mathcal{A}(W)$. Every chamber $C' \in \mathcal{R}(W_I)$ is the union of chambers of C of Wwith $C \subseteq C'$. The distinguished region $C_0 \in \mathcal{R}(W)$ determines a distinguished region $C'_0 \in \mathcal{R}(W_I)$ and $\mathcal{R}(W)^I$ are precisely the regions of W that make up C'_0 . Figure 5 illustrates the situation for \mathfrak{S}_4 .



FIGURE 5. Stereographic projection of reflection arrangement of \mathfrak{S}_4 . Permutations in black. The six reflections in red. Fundamental region in marker pink. Simple reflections for W_I in cyan. Black lines are reflection arrangement for W_I .

Whereas W_J is again a reflection group and we can hope to compute $W_J(q)$ inductively, the set W^J is not a group. We can, however, still compute $W^J(q)$ by inclusion-exclusion. For $w \in W$ define

$$D_R(w) := \{ \alpha \in \Delta : \ell(ws_\alpha) < \ell(w) \}.$$
⁽²⁾

We call $\alpha \in D_R(w)$ a (right) descent of w. By the Exchange Condition of Corollary 4.10, $D_R(w)$ are precisely those s_α that occur as the final simple reflection in some reduced expression of w.

Example 5.8 (Type A_{n-1}). Recall that for $\sigma \in \mathfrak{S}_n$, $\ell(\sigma)$ is the number of inversions. For a simple reflection $s_i = (i, i+1)$, $\sigma \circ (i, i+1)$ exchanges $\sigma(i)$ and $\sigma(i+1)$ in the one-line notation. Thus, if $\ell(\sigma \circ (i, i+1)) < \ell(\sigma)$, then this means that $\sigma(i) > \sigma(i+1)$, that is, *i* is a *descent* as commonly defined for permutations.

For $I \subseteq J \subseteq \Delta$, also define

$$D_I^J := \{ w \in W : I \subseteq D_R(w) \subseteq J \}$$
$$D_I := D_I^I = \{ w \in W : D_R(w) = I \}$$
$$W^J = D_{\emptyset}^{\Delta \setminus J} .$$

Note that the last line is *not* a definition but a straightforward consequence of the definition of W^{J} . Note also that

$$D_I^J = \biguplus_{I \subseteq K \subseteq J} D_K$$
 and thus $D_I^J(q) = \sum_{I \subseteq K \subseteq J} D_K(q)$.

Proposition 5.9. For $I \subseteq J \subseteq \Delta$

$$D_I^J(q) = \sum_{J \setminus I \subseteq K \subseteq J} (-1)^{|J \setminus K|} W^{\Delta \setminus K}(q)$$

PROOF. Note that for any $K \subseteq J$, we can combine above insights to get

$$W^{\Delta\setminus K}(q) = D^K_{\varnothing}(q) = \sum_{L\subseteq K} D_L(q).$$

Thus

$$\sum_{I \setminus I \subseteq K \subseteq J} (-1)^{|J \setminus K|} W^{\Delta \setminus K}(q) = \sum_{L \subseteq J} D_L(q) \sum_{(J \setminus I) \cup L \subseteq K \subseteq J} (-1)^{J \setminus K}$$

Using the binomial theorem, we get that the last sum is 1 if and only $(J \setminus I) \cup L = J$, that is, $I \subseteq L \subseteq J$. Hence

$$\sum_{J\setminus I\subseteq K\subseteq J} (-1)^{|J\setminus K|} W^{\Delta\setminus K}(q) = \sum_{I\subset L\subseteq J} D_L(q) = D_I^J(q).$$

For the next result we need the fact that relative to Δ , there is a unique element $w_0 \in W$ with $\ell(w_0) = |\mathcal{A}(W)|$. This is the **longest element** of Exercise 4.12.

Corollary 5.10.

$$\sum_{K\subseteq\Delta}\frac{(-1)^{|K|}}{W_K(q)} = \frac{q^{|\mathcal{A}|}}{W(q)}.$$

In particular for all $I \subseteq \Delta$

$$\sum_{K \subseteq \Delta} (-1)^{|K|} \frac{|W_I|}{|W_K|} = \frac{1}{|W^I|}.$$

PROOF. Take $I = J = \Delta$. Then Proposition 5.9 and Corollary 5.7 yields

$$q^{|\mathcal{A}|} = D_{\Delta}^{\Delta}(q) = \sum_{K \subseteq \Delta} (-1)^{|\Delta \setminus K|} W^{\Delta \setminus K}(q) = \sum_{K \subseteq \Delta} (-1)^{|K|} W^{K}(q) = \sum_{K \subseteq \Delta} (-1)^{|K|} \frac{W(q)}{W_{K}(q)} .$$

For the symmetric group something amazing happens. If we compute the length generating function, we get

$$\mathfrak{S}_{n}(q) = [n]_{q}[n-1]_{q}\cdots[2]_{q}[1]_{q} =: [n]_{q}!.$$
(3)

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Exercise 5.11. For a permutation $\tau \in \mathfrak{S}_n$ define $I(\tau) = (a_1, \ldots, a_n)$ by $a_i := \#\{j > i : \tau(i) > \tau(j)\}$. This defines a map $I : \mathfrak{S}_n \to [n-1] \times [n-2] \times \cdots \times [2] \times [1]$.

- (1) Show that I is injective. Hint: If $I(\sigma) = I(\tau)$, consider the maximal t with $\sigma^{-1}(t) \neq \tau^{-1}(t)$.
- (2) Conclude that I is bijective.
- (3) Prove (3) using I.

This factorization into polynomials all whose coefficients are 1 happens for all finite reflection groups.

THEOREM 5.12. For any finite reflection group W there are positive integers e_1, e_2, \ldots, e_k such that

$$W(q) = [e_1]_q [e_2]_q \cdots [e_k]_q.$$

6. The Coxeter complex

The reflection arrangement $\mathcal{A}(W)$ (and any arrangement, actually) induces a decomposition of the real vector space V, that we want to study now. Recall that a polyhedral cone is a set of the form $C = \{v \in V : \langle \beta_i, v \rangle \geq 0 \text{ for } i = 1, \ldots, m\}$. A linear hyperplane $H_{\alpha} \subseteq V$ is **valid** for C if $C \subseteq H_{\alpha}^{\geq}$ and a **face** of C is a subset $F = C \cap H_{\alpha}$, where H_{α} is a valid hyperplane. Note that every face of a cone is again a cone. We also let F = C be a face. The dimension of a cone is dim $C = \dim \text{span}(C)$.

For every $J \subseteq [m]$, the set

$$C_J := \{ v \in C : \langle \beta_i, v \rangle = 0 \text{ for } i \in J \}$$

is a face of C with respect to the valid hyperplane H_{β} with $\beta = \sum_{i \in J} \beta_i$. Conversely, it can be shown that every face is of the form C_J for some J.

If C is a simplicial cone, that is, if β_1, \ldots, β_m are linearly independent, then $C_J = C_{J'}$ if and only if J = J'. Moreover, dim $C_J = \dim V - |J|$. That is, the **codimension** of C_J is codim $C_J = \dim V - \dim C_J = |J|$. This gives us an easy way to count faces of a simplicial cone. The number of faces of codimension k is the coefficient of z^k of the polynomial

$$f_C(z) := \sum_{J \subseteq [m]} z^{|J|} = \sum_{l=0}^m \binom{m}{l} z^l = (1+z)^m.$$

We'll see next why it is advantageous to use the codimension instead of dimension.

For our reflection arrangements $\mathcal{A} = \mathcal{A}(W)$, the space V is decomposed into cones of various dimensions. Let Φ_0^+ be a fixed positive system. For a point $p \in V$, define $\kappa_{\alpha}(p) := \operatorname{sgn}\langle \alpha, p \rangle \in \{-1, 0, +1\}$ for each $\alpha \in \Phi_0^+$. Then

$$C_{\kappa} := \begin{cases} v \in V : & \langle \kappa_{\alpha} \alpha, v \rangle \geq 0 \text{ for } \kappa_{\alpha} \neq 0 \\ & \langle \alpha, v \rangle = 0 \text{ for } \kappa_{\alpha} = 0 \end{cases}$$

is a non-empty cone that contains p in its relative interior¹; see Figure 6 for an example.



FIGURE 6. Decomposition of \mathbb{R}^2 into faces of various dimensions by \mathcal{A} . The *f*-polynomial is $f_{\mathcal{A}}(z) = 6 + 6z + z^2$.

Since all chambers of \mathcal{A} are simplicial, the codimension of C_{κ} is $d(\kappa) := |\{\alpha \in \Phi^+ : \kappa_{\alpha} = 0\}|$. We define the **face vector** or *f*-vector $f(\mathcal{A})$ so that $f_k(\mathcal{A})$ is the number of cones C_{κ} of dimension k, for $k = 0, 1 \dots, n = \dim V$. We also define the *f*-polynomial as

$$f_{\mathcal{A}}(q) := f_n(\mathcal{A}) + f_{n-1}(\mathcal{A})q + \dots + f_0(\mathcal{A})q^n$$

Now, if W is not essential, that is if if $V^W = \{v \in V : wv = v \text{ for all } w \in W\} \neq 0$. Then we can restrict the action of W to $U := (V^W)^{\perp}$. Thus W is an essential reflection group in U with reflection arrangement $\mathcal{A}|_U$. If F is a face of \mathcal{A} , then $F \cap U$ is a face of $\mathcal{A}|_U$. The faces change but the codimension is left untouched.

For a reflection arrangement $\mathcal{A} = \mathcal{A}(W)$, we can interpret $f_k(\mathcal{A})$ algebraically. Again, let $\Delta \subseteq \Phi^+ \subset \Phi$ be fixed and let C be the fundamental domain with respect to Δ . Let W_J be a standard parabolic subgroup generated by s_α for $\alpha \in J \subseteq \Delta$. Recall that the rank of W_J is the codimension of the fixed space $V^{W_J} = L_J = \bigcap_{\alpha \in J} H_\alpha$, which is precisely |J|. Moreover J is a simple system for W_J , which we can identify with the face

$$C^J := \{ v : \langle \alpha, v \rangle = 0 \text{ for all } \alpha \in \Delta \setminus J, \langle \alpha, v \rangle \ge 0 \text{ for all } \alpha \in J \},\$$

which has codimension $|\Delta \setminus J|$. Note that wJ is a simple system for the parabolic subgroup wW_Jw^{-1} of the same rank and wJ is identified with wC^J . Let $\Phi_J^+ = \Phi^+ \cap \operatorname{cone}(J)$, which is a positive system for W_J . Then

$$C^J = \bigcap_{\alpha \in Pos_J} H^{\geq}_{\alpha} \cap \bigcap_{\alpha \in \Phi^+ \setminus Pos_J} H_{\alpha}$$

¹That is, the interior of C_{κ} relative to the linear subspace $\bigcap_{\kappa_{\alpha}=0} H_{\alpha}$.

Hence $wC^J = C^J$ if and only if $w \in W_{\Delta \setminus J}$ and hence wC^J for $w \in W^{\Delta \setminus J}$ represent the distinct simple systems for the parabolic subgroups that are conjugate to W_J , that is, wW_Jw^{-1} for $w \in W$. Therefore $(f_{\mathcal{A}(W)})_k$ is the number of simple systems of parabolic subgroups of rank k. For example for k = n, we have $J = \Delta$ and $W_J = W$. The number of simple systems is the number of regions of $\mathcal{A}(W)$, which is $W = W^{\varnothing}$. At the other extreme k = 0, we have $J = \emptyset$ and $W_J = \{e\}$. This group has only one simple system represented by $\bigcap \mathcal{A}(W)$ and $W^{\Delta} = \{e\}$. In summary

$$f_{\mathcal{A}(W)}(q) = \sum_{J \subseteq \Delta} |W^{\Delta \setminus J}| q^{|J|}.$$

Example 6.1 (Dihedral groups). Let \mathcal{D}_m be the dihedral symmetry group of an *m*-gon. The arrangement $\mathcal{A}_m = \mathcal{A}(\mathcal{D}_m)$ has *m* lines. The *f*-vector is then $f(\mathcal{A}_m) = (1, 2m, 2m)$.

Example 6.2 (Type A_{n-1}). For every $p \in \mathbb{R}^n$, there is a unique ordered set partition $M = (M_1, \ldots, M_k)$ with $M_1 \cup \cdots \cup M_k = [n], M_r \neq \emptyset$ and $M_r \cap M_s = \emptyset$ for all r < s. Such that

- (1) $p_i = p_j$ if and only if $i, j \in M_l$ for some l;
- (2) $p_i < p_j$ if and only if $i \in M_r$, $j \in M_s$ with r < s.

The cone containing p is precisely the set of $v \in V$ that give rise to the same set partition. The dimension of the cone is k, the length of the partition. The number of such *unordered* set partitions of n with k parts is counted by the famous **Stirling numbers** of the **second kind** S(n,k). They are given by S(0,0) = 1, S(n,k) = 0 for k > n or k = 0 and

$$S(n,k) = kS(n-1,k) + S(n-1,k-1).$$

Here is a table

S(n,k)	k = 1	2	3	4	5	6
n = 1	1					
2	1	1				
3	1	3	1			
4	1	7	6	1		
5	1	15	25	10	1	
6	1	31	90	65	15	1

It follows that $f_k(\mathcal{A}) = k!S(n,k)$, as we have k! ways to arrange the k parts of the partition. For example, for n = 3, we get $f(\mathcal{A}(\mathfrak{S}_3)) = (0, 1, 2! \cdot 3, 3! \cdot 1) = (0, 1, 6, 6)$, which is the f-vector for \mathcal{D}_3 but the triangle is embedded in 3-space. For n = 4, we get

$$f(\mathcal{A}(\mathfrak{S}_3)) = (0, 1, 14, 36, 24).$$

Exercise 6.3. Show the following identities of formal power series

(1) For fixed
$$k \ge 0$$

$$\sum_{n\ge k} S(n,k)x^n = \frac{x^k}{(1-x)(1-2x)\cdots(1-kx)}.$$
(2) For $k\ge 0$

$$\sum_{n\ge k} S(n,k)\frac{x^n}{n!} = \frac{1}{k!}(e^x-1)^k,$$
where $e^x = \sum_{h\ge 0} \frac{x^h}{h!}.$

We will compute the f-vector or rather the f-polynomial of a simplicial arrangement \mathcal{A} by a technique called **half-open** decomposition. Let C_0 be an arbitrary but fixed region. For any region $C \in \mathcal{R}(\mathcal{A})$ let S(C) be the collection of hyperplanes $H \in \mathcal{A}$ that separate C from C_0 . We define

$$\widehat{C} := C \setminus \bigcup_{H \in S(C)} H.$$

We call \hat{C} a half-open cone. Note that $\hat{C}_0 = C_0$ and that the half-open cone of $-C_0$ is the interior of $-C_0$.

Lemma 6.4. Let \mathcal{A} be a hyperplane arrangement with regions $\mathcal{R}(\mathcal{A})$. Then

$$V = \biguplus_{C \in \mathcal{R}(\mathcal{A})} \widehat{C} \,.$$

PROOF. Let $p \in C_0^{\circ}$ be arbitrary but fixed. Let $v \in V$ be an arbitrary point. If $v \in C^{\circ}$ for some region C, then \widehat{C} is unique region containing v. Otherwise, consider $q := v - \varepsilon(v - p)$ for $\varepsilon > 0$. For $\varepsilon > 0$ sufficiently small, q is contained in the interior of the unique $C \in \mathcal{R}(\mathcal{A})$ for which $v \in \partial C$. Let $H_{\alpha} \in \mathcal{A}$ be a hyperplane containing v and assume that $C_0 \subset H_{\alpha}^{\geq}$. Then $\langle \alpha, v \rangle = 0$ and, by construction, $\langle \alpha, q \rangle = \varepsilon \langle \alpha, p \rangle > 0$, since $p \in C_0^{\circ}$. Thus $C \subseteq H_{\alpha}^{\geq}$. This shows that $v \in \widehat{C}$.

Assume that C' is another region with $v \in \partial C'$. Then there is a wall H of C' separating C' from C. By construction of C, we have that q and and p lie on the same side, that is, H separates C' from C_0 and hence $v \notin \widehat{C'}$.



Let $C = \{v : \langle a_i, v \rangle \ge 0 \text{ for } i = 1, ..., n\}$ such that all H_{α_i} are walls of C. Let $D = D(C) := \{i : C_0 \subseteq H_{\alpha_i}^{\le}\}$. Then

$$\widehat{C} = \{ v : \langle \alpha_i, v \rangle \ge 0 \text{ for } i \notin D \text{ and } \langle \alpha_i, v \rangle > 0 \text{ for } i \in D \}$$

The faces of \widehat{C} are precisely those faces F of C that do not lie in any of the hyperplanes H_{α_i} for $i \in D$. If C is simplicial, then they are easy to count:

$$f_{\widehat{C}}(z) = \sum_{J \subseteq [m] \setminus D} z^{|J|} = (1-z)^{m-|D|}.$$

Note that if $0 \le |D(C)| \le m$ and we define the *h*-polynomial

$$h_{\mathcal{A}}(z) = \sum_{C \in \mathcal{R}(\mathcal{A})} z^{m-|D(C)|} = h_m(\mathcal{A}) + h_{m-1}(\mathcal{A})z + \dots + h_0(\mathcal{A})z^m$$

THEOREM 6.5. Let \mathcal{A} be a simplicial hyperplane arrangement with base region $C_0 \in \mathcal{R}(\mathcal{A})$ and h-polynomial $h_{\mathcal{A}}(z)$. Then

$$f_{\mathcal{A}}(z) = h_{\mathcal{A}}(z+1)$$

PROOF. It follows from Lemma 6.4 that for every face F of \mathcal{A} , there is a unique $C \in \mathcal{R}(\mathcal{A})$ with $F \subseteq \widehat{C}$. Thus

$$f_{\mathcal{A}}(z) = \sum_{C \in \mathcal{R}(\mathcal{A})} f_{\widehat{C}}(z) = \sum_{C \in \mathcal{R}(\mathcal{A})} (1+z)^{m-|D(C)|} = \sum_{k=0}^{m} h_k(\mathcal{A})(1+z)^{m-k}.$$



Our notation does not emphasize which base region we selected for the computation of the half-open decomposition or $h_{\mathcal{A}}(z)$. But it does not matter.

Corollary 6.6. The h-polynomial is independent of the base region C_0 .

PROOF. Note that $h_{\mathcal{A}}(z) = f_{\mathcal{A}}(z-1)$.

Corollary 6.7 (Dehn–Sommerville equations). If \mathcal{A} is an essential simplicial arrangement in n-dimensional space, then $h_{\mathcal{A}}(z) = z^n h_{\mathcal{A}}(\frac{1}{z})$, that is,

$$h_k(\mathcal{A}) = h_{n-k}(\mathcal{A})$$

PROOF. A wall of C separates C from C_0 if and only if it does not separate C from $-C_0$. Thus, the *h*-polynomial with respect to $-C_0$ as the base region is precisely

$$\sum_{C \in \mathcal{R}(\mathcal{A})} z^{|D(C)|} = z^n h_{\mathcal{A}}(\frac{1}{z})$$

Since the $h_{\mathcal{A}}(z)$ is independent of the choice of a base region now complete the proof.

Note that we can express the *h*-polynomial of a reflection arrangement $\mathcal{A}(W)$ algebraically as follows. Recall from (2) that $\alpha \in \Delta$ is a **right descent** of $w \in W$ if $\ell(ws_{\alpha}) < \ell(w)$ and $D_R(w)$ is the **descent set** of w. By the Exchange condition of Corollary 4.10, $\alpha \in D_R(w)$ if and only if there is a reduced expression that ends in s_{α} . Using Construction 4.5, this means that $t := ws_{\alpha}w^{-1}$ is a reflection in a wall of wC_0 that separates wC_0 from C_0 . That is

$$|D(wC_0)| = |D_R(w)|.$$

We write $d(w) := |D_R(w)|$ and define the Eulerian polynomial

$$A_W(z) := \sum_{w \in W} z^{d(w)} \,.$$

The naming is inspired by the **Eulerian numbers** A(n,k) that count the number of permutations $\sigma \in \mathfrak{S}_n$ with k descents, that is, indices $1 \leq i < n$ with $\sigma(i) > \sigma(i+1)$. For example

$$A_{\mathfrak{S}_3}(z) = 1 + 4z + z^2$$
 $A_{\mathfrak{S}_4}(z) = 1 + 11z + 11z^2 + 1;$

see Figure 8.



FIGURE 8. Half-open decomposition for reflection arrangement of symmetric group

7. Classification of finite reflection groups

In this section we will classify all the finite reflection groups. For that we will first seek a compact way to encode reflection groups. Let W be a reflection group that acts essentially on the *n*-dimensional real vector space V. Let Φ be a root system consisting of vectors of unit length and let $\Delta = \{\alpha_1, \ldots, \alpha_n\}$ be simple system. Remember that $s_{\alpha_i}, s_{\alpha_j}$ for $i \neq j$ generates a rank-2 reflection group $\mathcal{D}_{m_{ij}}$ for some $m_{ij} \geq 2$. Since α_i, α_j is a simple system for \mathcal{D}_{m_ij} , we have that $s_{\alpha_i}s_{\alpha_j}$ is a rotation by $\frac{2\pi}{m_{ij}}$. Hence $(s_{\alpha_i}s_{\alpha_j})^{m_{ij}} = e$ and

$$\langle \alpha_i, \alpha_j \rangle = -\cos \frac{\pi}{m_{ij}}$$

We define the **Coxeter matrix** $M = (m_{ij})_{i,j}$. Let denote the Gram matrix of the simple system by A with entries

$$A_{ij} = \langle \alpha_i, \alpha_j \rangle = -\cos \frac{\pi}{m_{ij}}, \qquad (4)$$

where $m_{ii} = 1$ and $A_{ii} = 1$. Up to labelling the individual roots, the matrix A is independent of the choice of a simple system. It is more customary to record M by defining the **Coxeter graph** Γ , which is a simple undirected graph on nodes $[n] = \{1, \ldots, n\}$ such that ij is an edge iff $m_{ij} \ge 2$. The edge ij carries an edge label m_{ij} iff $m_{ij} \ge 3$.

We call W irreducible if the Coxeter graph is connected. For example the Coxeter graph of the dihedral group $I_2(2)$ consists on two isolated nodes. If $V_1
in V_2
in \cdots
in V_k = [n]$ are the node sets of the connected components of Γ , then $W_h = \langle s_i : i \in V_h \rangle$ defines a (standard) parabolic subgroup and $W = W_1 \times W_2 \times \cdots \times W_n$. Hence, it suffices to classify the irreducle reflection groups. Figure 9 shows the Coxeter graphs for the dihedral groups as well as the groups of types A_n and B_n and some more.



FIGURE 9. Coxeter graphs of all reflection groups.

The Coxeter graph is connected if and only if the Gram matrix A is **indecomposable**, that is, if there is no partition $I \uplus J = [n]$ such that $A_{ij} = 0$ for all $i \in I, j \in J$. Moreover, as a Gram matrix, A is symmetric and **positive semidefinite**, i.e., $x^t A x \ge 0$ for all $x \in V$. Moreover, A is **positive definite** if additionally $x^t A x = 0$ implies x = 0.² We need the following lemma from matrix theory.

Lemma 7.1. Let A be an indecomposable and positive semidefinite matrix such that $A_{ij} \leq 0$ for all $i \neq j$.

a) ker $A = \{x : x^t A x = 0\}$

- b) dim ker $A \leq 1$ and if = 1, then ker(A) is spanned by a vector with all entries positive.
- c) The eigenspace for the smallest eigenvalue is 1-dimensional an spanned by vector with strictly positive components.

²Yes, we should consistently write $\langle x, Ax \rangle$ but this is too much.

PROOF. a) Since A is positive definite and hence the Gram matrix of some vector configuration, there is G with $A = G^t G$ and hence $x^t A x = ||Gx||^2$. Thus, if $x^t A x = 0$, then Gx = 0 and hence Ax = 0. The direction Ax = 0 implies $x^t A x = 0$ is clear. (Here we used the positive semidefiniteness.)

b) Let $x \in \ker A$ with $x \neq 0$. Define z by $z_i = |x_i|$. Then

$$0 \leq z^{t}Az = \sum_{i,j} |x_{i}|A_{ij}|x_{j}| \leq \sum_{i,j} x_{i}A_{ij}x_{j} = 0,$$

where we used $A_{ij} \leq 0$, we conclude that Az = 0. Define $I := \{i : z_i = 0\}$ and $J := [n] \setminus I$. For every i, we have

$$0 = \sum_{j \in J} A_{ij} z_j$$

Again, since $A_{ij} \leq 0$ and $z_j > 0$ for $j \in J$, we get $A_{ij} = 0$ for all $i \in I$ and $j \in J$. Since A is assumed to be irreducile, this means $I = \emptyset$. This shows that z > 0. In fact the argument shows that every $x \neq 0$ with Ax = 0 has to have all coordinates nonzero. However if there is $x' \in \ker A$ linearly independent from x, then $\alpha x + \beta x'$ has a zero component for some $\alpha, \beta \in \mathbb{R}$. This shows b).

For c), we note that if $\lambda \ge 0$ is the smallest eigenvalue, then $A' := A - \lambda I$ is still positive semidefinite, irreducile and non-positive off-diagonal entries. The kernel of A' is the eigenspace of A and is 1-dimensional by a).

Every graph Γ on nodes [n] with edge labels $m_{ij} \geq 3$ gives rise to a matrix A_{Γ} as defined (4). We call Γ positive (semi)definite if A_{Γ} is positive (semi)definite. A **subgraph** Γ' is obtained from Γ by deleting nodes together with incident edges or decreasing the label on some edges.

Proposition 7.2. Let Γ be a connected, positive definite graph Γ , then every subgraph Γ' is positive definite.

PROOF. Suppose first that Γ' is obtained by only deleting nodes and let $J \subsetneq [n]$ be the node set of Γ' . The matrix $A_{\Gamma'}$ is obtained from A_{Γ} by restricting to rows and columns indexed by J. In particular, if $A_{\Gamma'}$ is not of full rank, then by Lemma 7.1a), there is an x with $\operatorname{supp}(x) = \{i : x_i \neq 0\} \subseteq J$ and $x^t A_{\Gamma} x = 0$. But if $x \neq 0$, then it follows from Lemma 7.1b) that J = [n], which shows $\Gamma = \Gamma'$ and Γ was positive definite.

Thus, it suffices to assume that Γ' has the same node set but $m'_{ij} \leq m_{ij}$ for all edges ij. That is, $A_{ij} = -\cos(\frac{\pi}{m_{ij}}) \leq -\cos(\frac{\pi}{m'_{ij}}) = A'_{ij}$. Now if there is $x \neq 0$ with $x^t A' x \leq 0$, then we compute

$$0 \ \leq \ \sum_{i,j} a_{ij} |x_i| |x_j| \ \leq \ \sum_{i,j} a_{ij}' |x_i| |x_j| \ \leq \ \sum_{i,j} a_{ij}' x_i x_j \ \leq \ 0 \, .$$

The vector z of absolute values of x thus satisfies $z^t A z = 0$, which contradicts our assumption that Γ and hence $A = A_{\Gamma}$ is positive definite.

THEOREM 7.3. The only connected, positive definite graphs are those in Figure 9.

PROOF. 1. Γ is a tree (i.e. does not contain a cycle). The matrix A of a cycle with all edge labels $m_{ij} = 3$ consists of cyclic shifts of the row $(\rho, 1, \rho, 0, \dots, 0)$, where $\rho = -\cos(\frac{\pi}{3}) = -\frac{1}{2}$. Hence $\mathbf{1}^t A \mathbf{1} = 0$ and a cycle cannot occur as a subgraph.

This means that Γ is a tree.

If Γ is not of type A_n , then it has node of degree ≥ 3 .

2. Γ has no node of degree ≥ 4 .

Otherwise, we could find as a subgraph, the graph Γ' with nodes 1, 2, 3, 4, 5 and edges is for $i = 1, \ldots, 4$.

.

The corresponding matrix $A_{\Gamma'}$ is

$$\begin{pmatrix} 1 & & -\frac{1}{2} \\ & 1 & & -\frac{1}{2} \\ & & 1 & -\frac{1}{2} \\ & & 1 & -\frac{1}{2} \\ & & 1 & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & 1 \end{pmatrix}$$

which is not positive definite.

2. Γ has a unique node of degree = 3

The following illustrates the situation and hints at a generalization



3. The three paths starting at the branch point cannot be all ≥ 2 long. The following illustrates the situation



In a similar manner, one checks that the following subgraphs cannot occur³:



This shows that if W is a finite reflection group, then its Coxeter graph has to belong to one of the 10 types shown in Figure 9. To construct a finite reflection group for each of the 10 types, let Γ be one of these on n nodes. The matrix $A = A_{\Gamma} \in \mathbb{R}^{n \times n}$ is positive definite and there is a factorization $A = G^{t}G$ for some full-rank matrix $G \in \mathbb{R}^{n \times n}$. Let $\alpha_{1}, \ldots, \alpha_{n}$ be the column vectors. Note that $A_{ii} = 1$ and all

³The figure is taken from [3]

 α_i are unit vectors. Define hyperplanes $H_i = H_{\alpha_i}$ and reflections $s_i = s_{\alpha_i}$ and let W be the subgroup of $\operatorname{GL}(\mathbb{R}^n)$ generated by these reflections. Using the fact that $\langle \alpha_i, \alpha_j \rangle \leq 0$ for all $i \neq j$ we can employ ideas similar to those of Section 3 to show that for every α_i , the orbit $W\alpha_i$ is finite. If we let Φ be the union of all these finite orbits, then this allows us to show that $W \to \mathfrak{S}(\Phi)$ is a monomorphism and hence W is finite; cf. Exercise 2.3.

THEOREM 7.4. The irreducible finite reflection groups are, up to isomorphism, in one-to-one correspondence with the Coexeter graphs of Figure 9.

CHAPTER 2

Arrangements and simpliciality

The beginning of this chapter essentially follows the first chapters of the book Arrangements of Hyperplanes by Orlik and Terao [4].

1. Arrangements of hyperplanes

Definition 1.1. Let K be a field, $\ell \in \mathbb{N}$, and $V := K^{\ell}$. An **arrangement of hyperplanes** (or ℓ -arrangement) (\mathcal{A}, V) (or \mathcal{A} for short) is a finite set of hyperplanes \mathcal{A} in V.

Example 1.2. Let $K = \mathbb{F}_q$ be a finite field and $V = \mathbb{F}_q^{\ell}$. The set of all linear hyperplanes in V is an arrangement of hyperplanes.

Remark 1.3. Let e_1, \ldots, e_ℓ be a basis of V and $x_1, \ldots, x_\ell \in V^*$ be the dual basis. The symmetric algebra $S(V^*)$ is a polynomial algebra $K[x_1, \ldots, x_\ell]$.

Each hyperplane H in an arrangement is the kernel of a linear form α_H (= polynomial of degree 1 in $S(V^*)$). However, for any unit $a \in K^{\times}$, the linear form $a \cdot \alpha_H$ defines the same hyperplane. So in a certain sense, an arrangement of hyperplanes may equivalently be defined as a set of points in the projective space $\mathbb{P}(V^*)$.

Since α_H is defined only up to scalars, it will be convenient to write

$$f \doteq g \quad \Leftrightarrow \quad \exists a \in K^{\times} : f = a \cdot g.$$

Definition 1.4. Let \mathcal{A} be an arrangement and write α_H , $H \in \mathcal{A}$ for defining linear forms. The product

$$Q(\mathcal{A}) \doteq \prod_{H \in \mathcal{A}} \alpha_H$$

is called the **defining polynomial** of \mathcal{A} .



FIGURE 1. The arrangement of type A_3 .

Example 1.5. The arrangement \mathcal{A} of type A_3 has 6 hyperplanes in $V = \mathbb{R}^3$ (see Figure 1). With respect to the standard basis x, y, z of V^* , the hyperplanes of \mathcal{A} are the kernels of the linear forms

(1,0,0), (0,1,0), (0,0,1), (1,1,0), (0,1,1), (1,1,1).

We have $S(V^*) \cong K[x, y, z]$ and

$$Q(\mathcal{A}) = xyz(x+y)(y+z)(x+y+z)$$

Example 1.6. The arrangement in $V = K^{\ell}$ defined by

$$Q(\mathcal{A}) = \prod_{i=1}^{\ell} x_i$$

is called the **boolean arrangement**.

Example 1.7. For $1 \le i < j \le \ell$ let $H_{i,j} = \ker(x_i - x_j)$. The arrangement in $V = \mathbb{R}^{\ell}$ defined by

$$Q(\mathcal{A}) = \prod_{1 \le i < j \le \ell} (x_i - x_j)$$

consisting of all the hyperplanes $H_{i,j}$ is called the **braid arrangement**.

Exercise 1.8. Compute the number $|\mathcal{A}|$ of hyperplanes for the arrangements in examples 1.6, 1.7, 1.2. **Definition 1.9.** Let \mathcal{A} be an arrangement. The set

$$L(\mathcal{A}) := \left\{ \bigcap_{H \in U} H \mid U \subseteq \mathcal{A} \right\}$$

is called the **intersection lattice** of \mathcal{A} . It is partially ordered by reverse inclusion:

$$X \leq Y \iff Y \subseteq X, \quad \text{for } X, Y \in L(\mathcal{A}).$$

If $X \in L(\mathcal{A})$, then the **rank** r(X) of X is defined as $r(X) := \ell - \dim X$, i.e. the codimension of X and the rank of the arrangement \mathcal{A} is defined as $r(\mathcal{A}) := r(T(\mathcal{A}))$ where $T(\mathcal{A}) := \bigcap_{H \in \mathcal{A}} H$ is the **center** of \mathcal{A} . The arrangement \mathcal{A} is called **central** if $0 \in H$ for all $H \in \mathcal{A}$. An ℓ -arrangement \mathcal{A} is called **essential** if $r(\mathcal{A}) = \ell$.

Example 1.10. The braid arrangement \mathcal{A} is not essential:

$$T(\mathcal{A}) = \langle (1, \dots, 1) \rangle, \quad r(\mathcal{A}) = \ell - \dim(T(\mathcal{A})) = \ell - 1.$$

Example 1.11. Recall the arrangement \mathcal{A} of type A_3 . It is essential and of rank 3. The intersection lattice consists of 0, $V, H \in \mathcal{A}$ and the subspaces generated by

$$(0, 0, 1), (0, 1, 0), (1, 0, 0), (0, 1, -1), (1, 0, -1), (1, -1, 0), (1, -1, 1), (1, -1,$$

Definition 1.12. Let \mathcal{A} be an arrangement. For $X \in L(\mathcal{A})$, we define the localization

$$\mathcal{A}_X := \{ H \in \mathcal{A} \mid X \subseteq H \}$$

of \mathcal{A} at X, and the **restriction of** \mathcal{A} to X, (\mathcal{A}^X, X) , where

$$\mathcal{A}^X := \{ X \cap H \mid H \in \mathcal{A} \setminus \mathcal{A}_X \}.$$

Example 1.13. Localizations and restrictions in the arrangement of type A_3 (Picture).

Definition 1.14 ([4, 2.13, 2.15]). Let (\mathcal{A}_1, V_1) and (\mathcal{A}_2, V_2) be arrangements. The **product** of \mathcal{A}_1 and \mathcal{A}_2 is the arrangement $(\mathcal{A}_1 \times \mathcal{A}_2, V_1 \oplus V_2)$ where

$$\mathcal{A}_1 \times \mathcal{A}_2 := \{ H \oplus V_2 \mid H \in \mathcal{A}_1 \} \cup \{ V_1 \oplus H \mid H \in \mathcal{A}_2 \}.$$

An arrangement (\mathcal{A}, V) is called **reducible** if there exist arrangements (\mathcal{A}_1, V_1) and (\mathcal{A}_2, V_2) such that $(\mathcal{A}, V) = (\mathcal{A}_1 \times \mathcal{A}_2, V_1 \oplus V_2)$. Otherwise (\mathcal{A}, V) is called **irreducible**.

Example 1.15. The arrangement in Figure 2 is called a **near pencil**. It is reducible.



FIGURE 2. A near pencil arrangement.

2. Simplicial arrangements

Definition 2.1. Let $\ell \in \mathbb{N}$, $V := \mathbb{R}^{\ell}$, and \mathcal{A} an arrangement in V. Let $\mathcal{K}(\mathcal{A})$ be the set of connected components (**chambers**) of $V \setminus \bigcup_{H \in \mathcal{A}} H$. If every chamber K is an **open simplicial cone**, i.e. there exist $\alpha_1^{\vee}, \ldots, \alpha_{\ell}^{\vee} \in V$ such that

$$K = \left\{ \sum_{i=1}^{\ell} a_i \alpha_i^{\vee} \mid a_i > 0 \quad \text{for all} \quad i = 1, \dots, \ell \right\} =: \langle \alpha_1^{\vee}, \dots, \alpha_\ell^{\vee} \rangle_{>0},$$

then \mathcal{A} is called a **simplicial arrangement**.



FIGURE 3. A simplicial arrangement in \mathbb{R}^2 , a representation of a simplicial arrangement in \mathbb{R}^3 in the projective plane.

Example 2.2. (1) Figure 3 displays examples for $\ell = 2$ and $\ell = 3$.

(2) Let W be a real reflection group, R the set of roots of W. For $\alpha \in V^*$ we write $\alpha^{\perp} = \ker(\alpha)$. Then $\mathcal{A} = \{\alpha^{\perp} \mid \alpha \in R\}$ is a simplicial arrangement.

Theorem 2.3 (Deligne, 1972). The complement of a complexified finite simplicial arrangement is $K(\pi, 1)$.

For dimension three, there is a catalogue of known simplicial arrangements [2] and we have a complete list of simplicial arrangements with at most 27 lines [1]. There are a little less than 100 "sporadic" arrangements in the catalogue. For most of them, we have no satisfactory explanation yet. H.S.M. Coxeter writes

"[...] the diagrams which profess to portray these known polygrams are strangely unintelligible."

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